

APS 425 – Fall 2015

Time Series Analysis:
ARIMA Models

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Topics

- Typical time series plot
- Pattern recognition in auto and partial autocorrelations
- Stationarity & invertibility

Partial autocorrelations

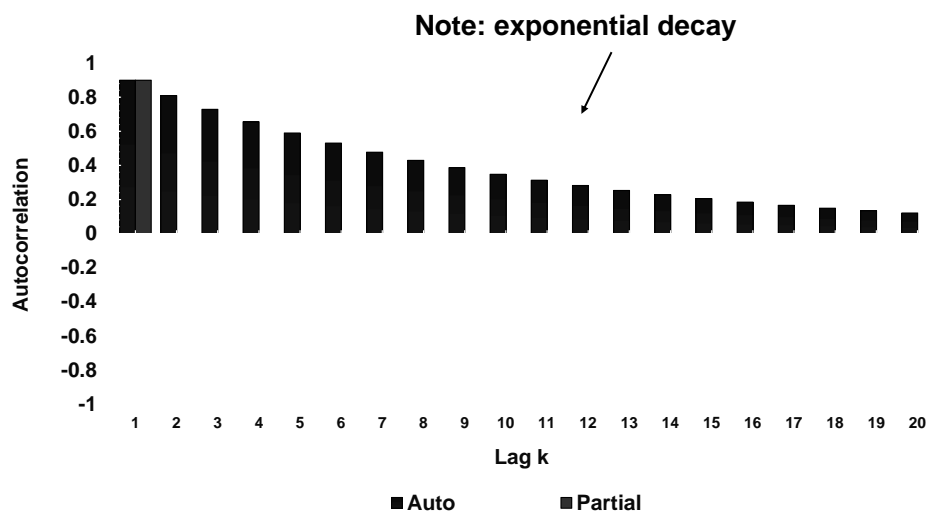
- Used to identify pure AR models
- Estimate a sequence of AR(k) models, and report the last coefficient estimate, ϕ_{kk} , for each lag k:

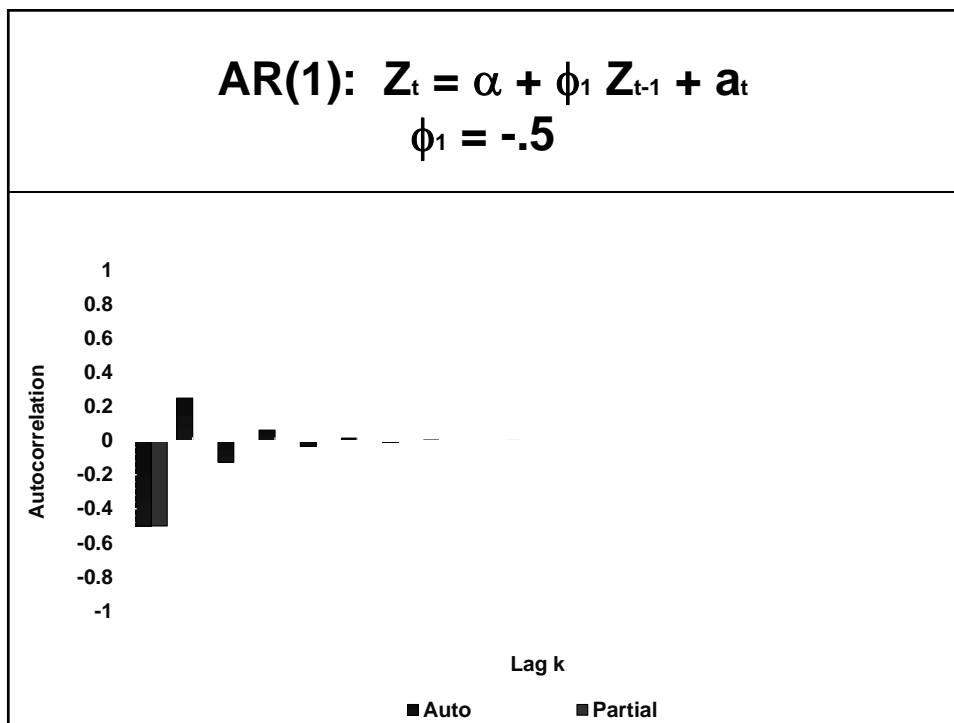
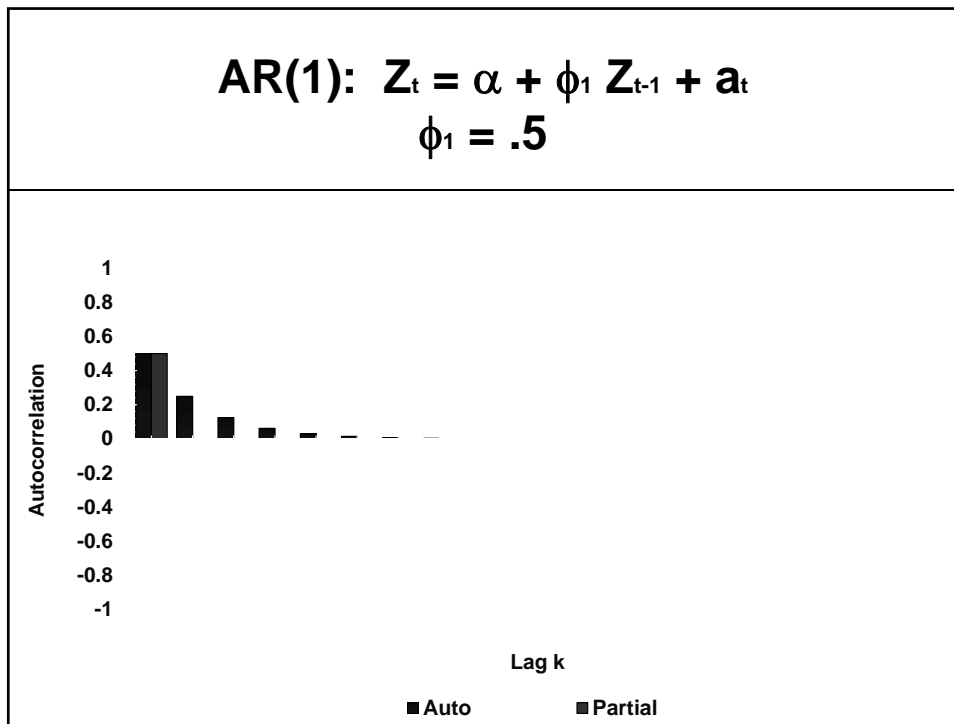
$$AR(k): Z_t = \alpha + \phi_{1k} Z_{t-1} + \dots + \phi_{kk} Z_{t-k} + a_t$$

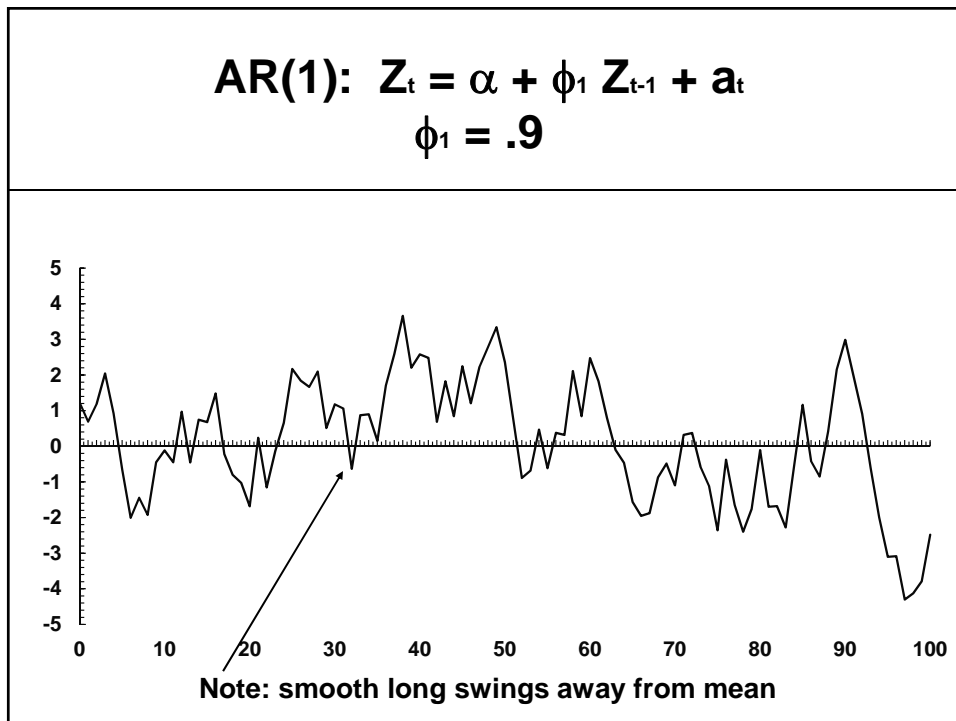
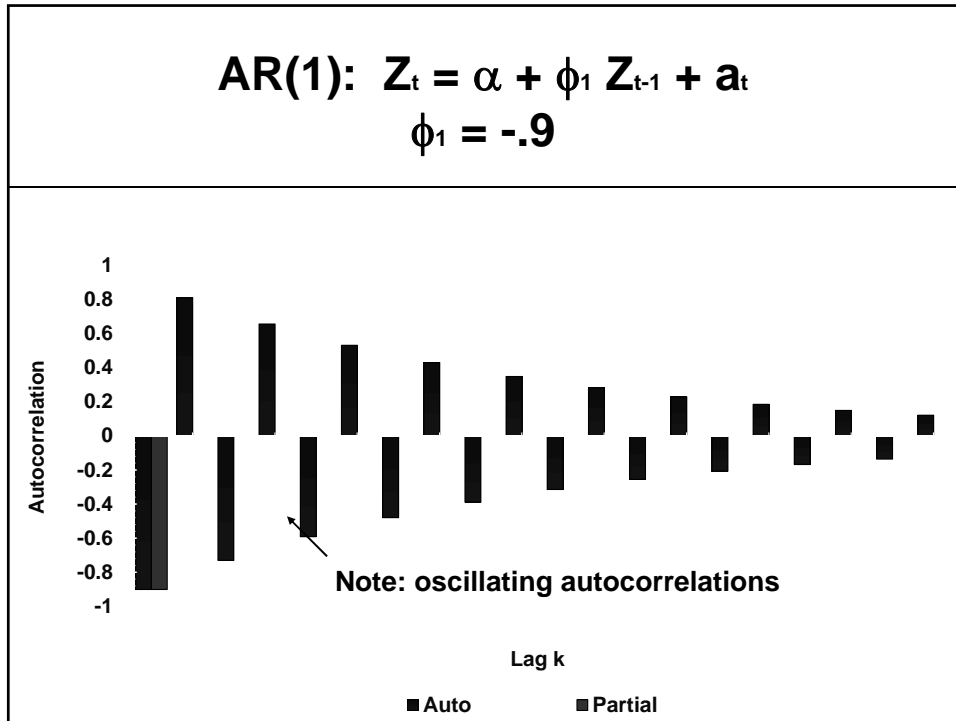
- Graph the pacf coefficients, ϕ_{kk} , and see where they become zero, which implies that the right model is a (k-1)th order AR process

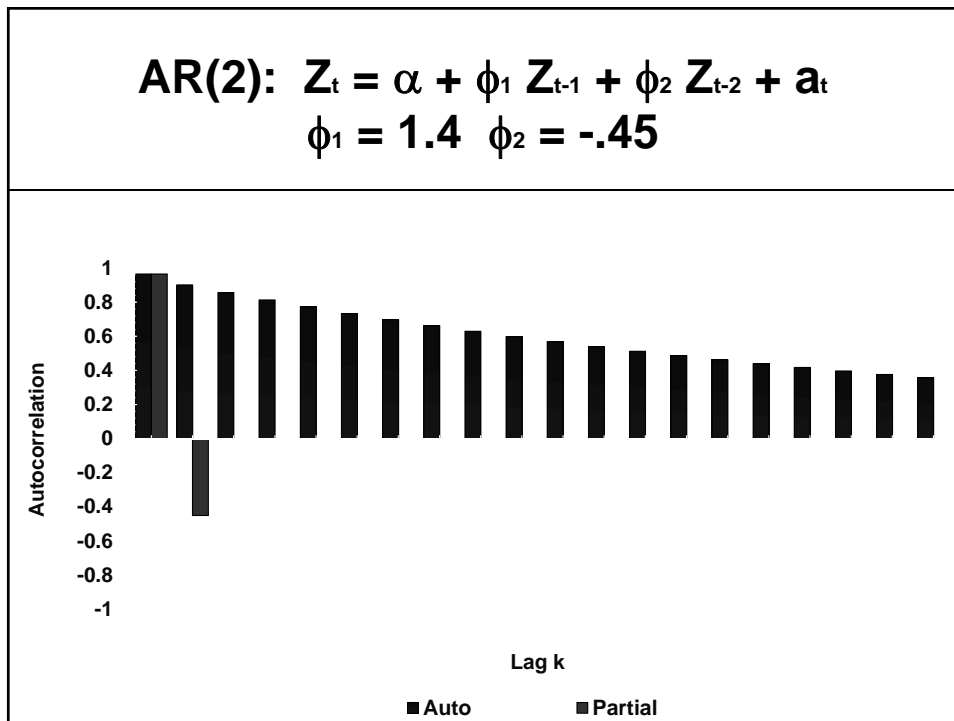
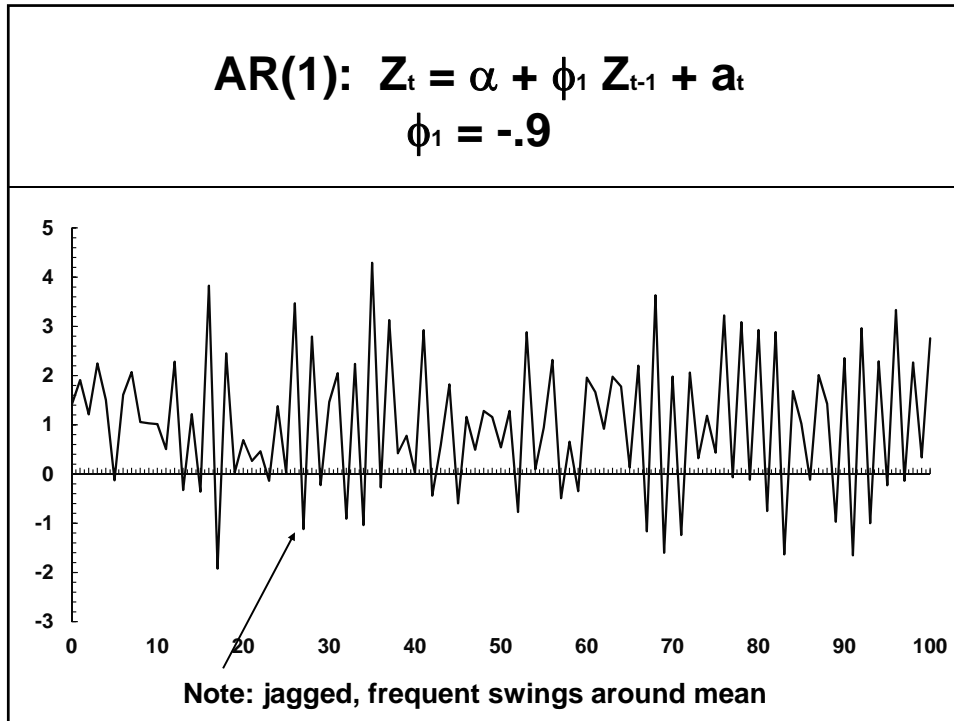
$$AR(1): Z_t = \alpha + \phi_1 Z_{t-1} + a_t$$

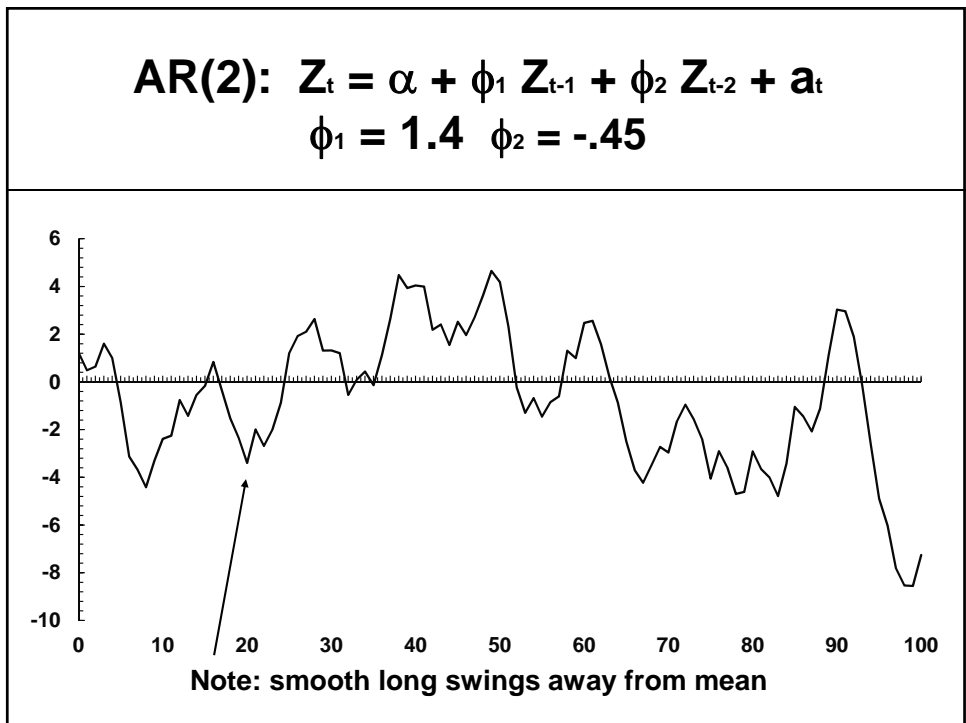
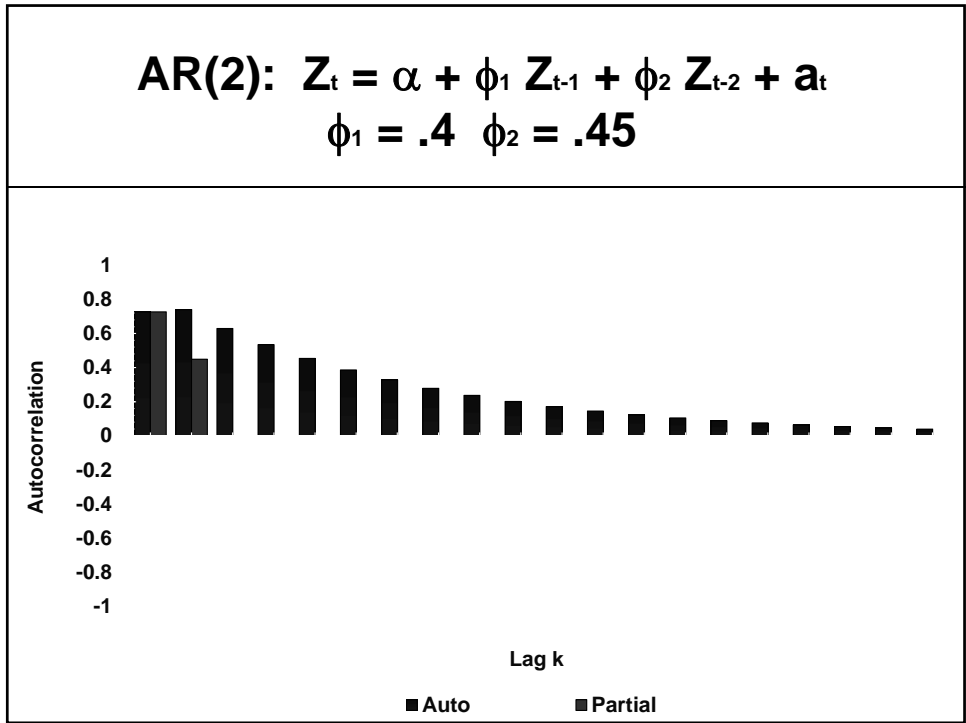
$$\phi_1 = .9$$







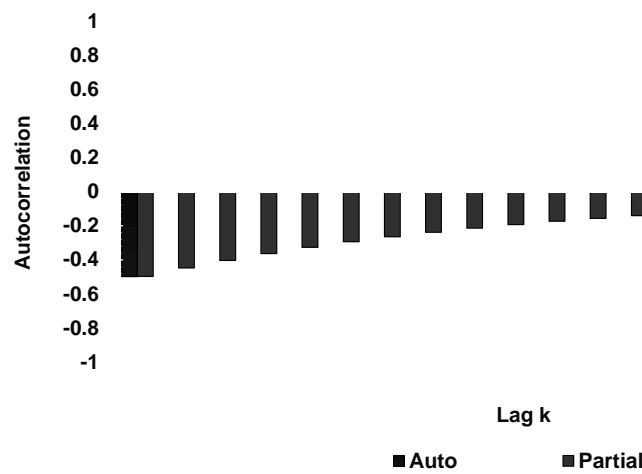


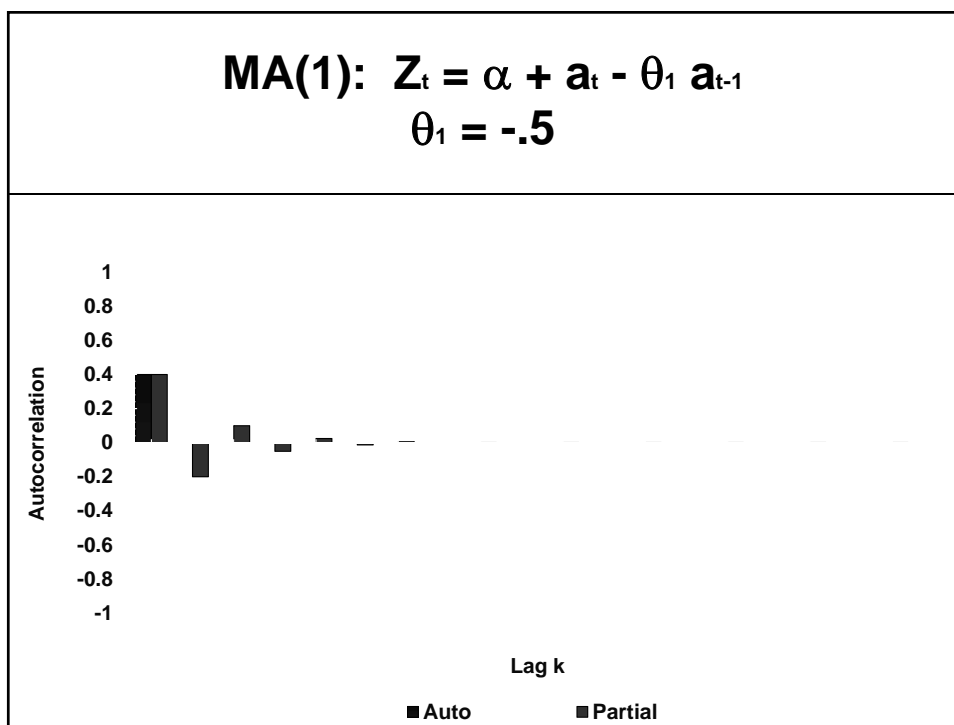
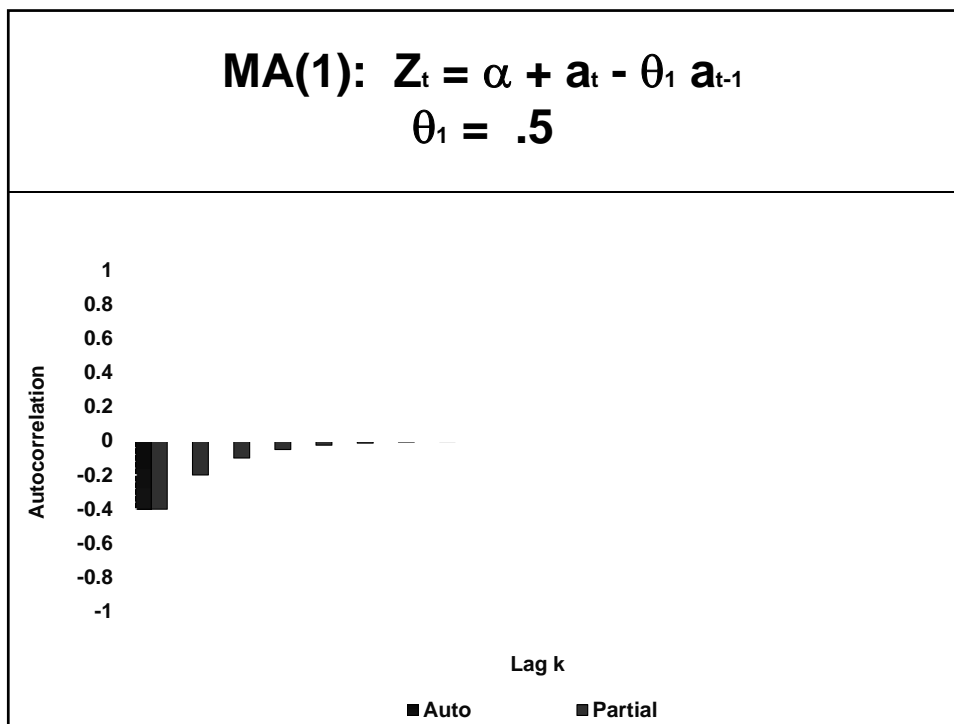


Autoregressive Models: Summary

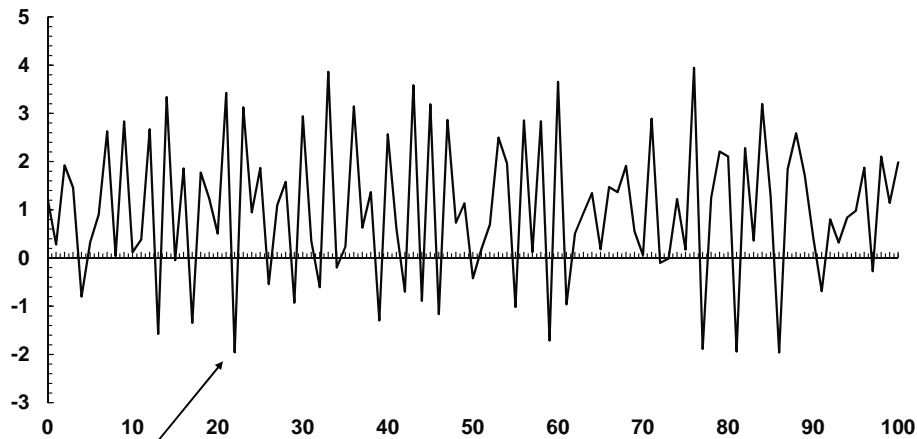
- 1) Autocorrelations decay or oscillate
- 2) Partial Autocorrelations cut-off after lag p , for AR(p) model
- 3) Stationarity is a big issue
 - very slow decay in autocorrelations
 - should you difference?

$$\text{MA}(1): Z_t = \alpha + a_t - \theta_1 a_{t-1}$$
$$\theta_1 = .9$$





$$\text{MA}(1): Z_t = \alpha + a_t - \theta_1 a_{t-1}$$
$$\theta_1 = .9$$



Note: jagged, frequent swings around the mean

Moving Average Models: Summary

- 1) Autocorrelations cut off after lag q for MA(q) model
- 2) Partial autocorrelations decay or oscillate
 - because an MA model is equivalent to an infinite order AR process
- 3) Note that Eviews uses a different convention for the sign of MA coefficients
 - Estimate of MA coefficient is $-.75$ for IMA(1,1) model of inflation, in BJ notation it would be $.75$

Autoregressive Moving Average Models

$$\text{ARMA}(p,q): Z_t = \alpha + \phi_1 Z_{t-1} + \dots + \phi_p Z_{t-p} + a_t - \theta_1 a_{t-1} - \dots - \theta_q a_{t-q}$$

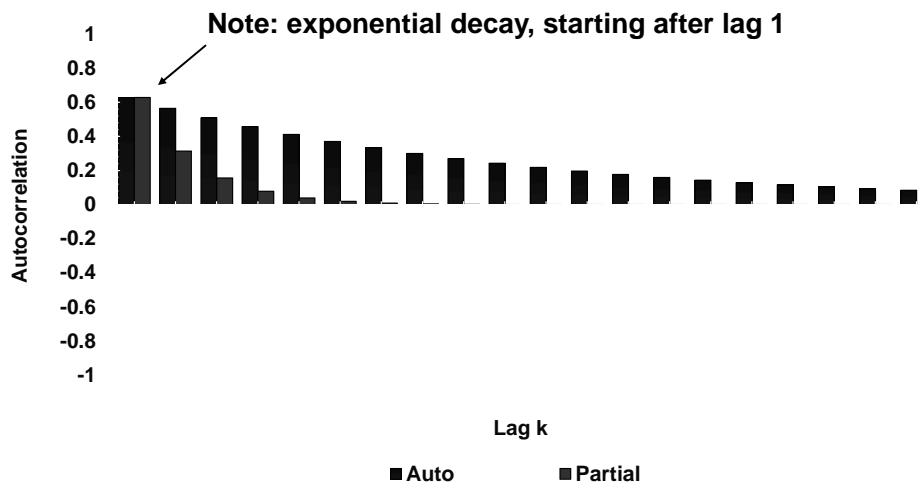
Combines both AR & MA characteristics:

- equivalent to infinite order MA process
 - if stationary

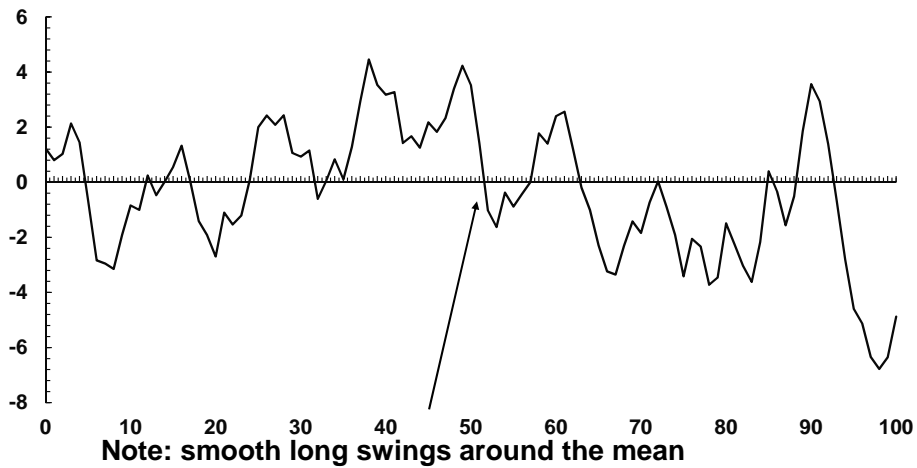
- equivalent to infinite order AR process
 - if “invertible”

$$\text{ARMA}(1,1): Z_t = \alpha + \phi_1 Z_{t-1} + a_t - \theta_1 a_{t-1}$$

$$\phi_1 = .9, \theta_1 = .5$$



$$\text{ARMA}(1,1): Z_t = \alpha + \phi_1 Z_{t-1} + a_t - \theta_1 a_{t-1}$$
$$\phi_1 = .9, \theta_1 = .5$$



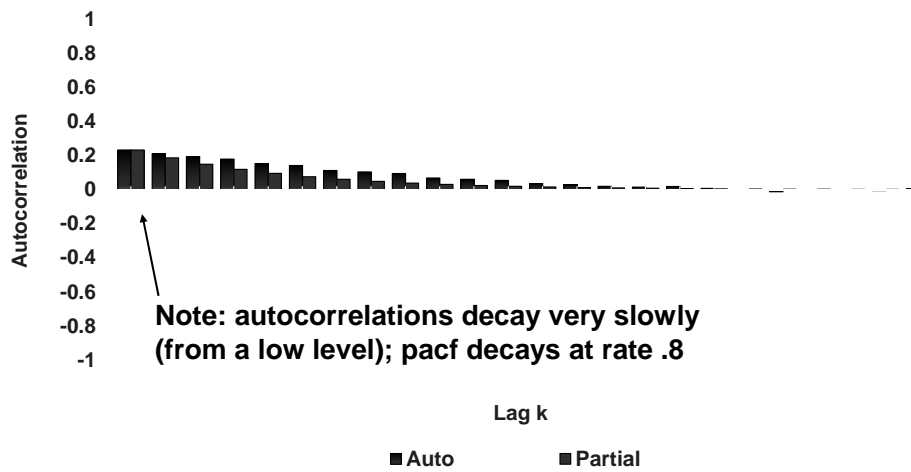
Autoregressive Moving Average Models: Summary

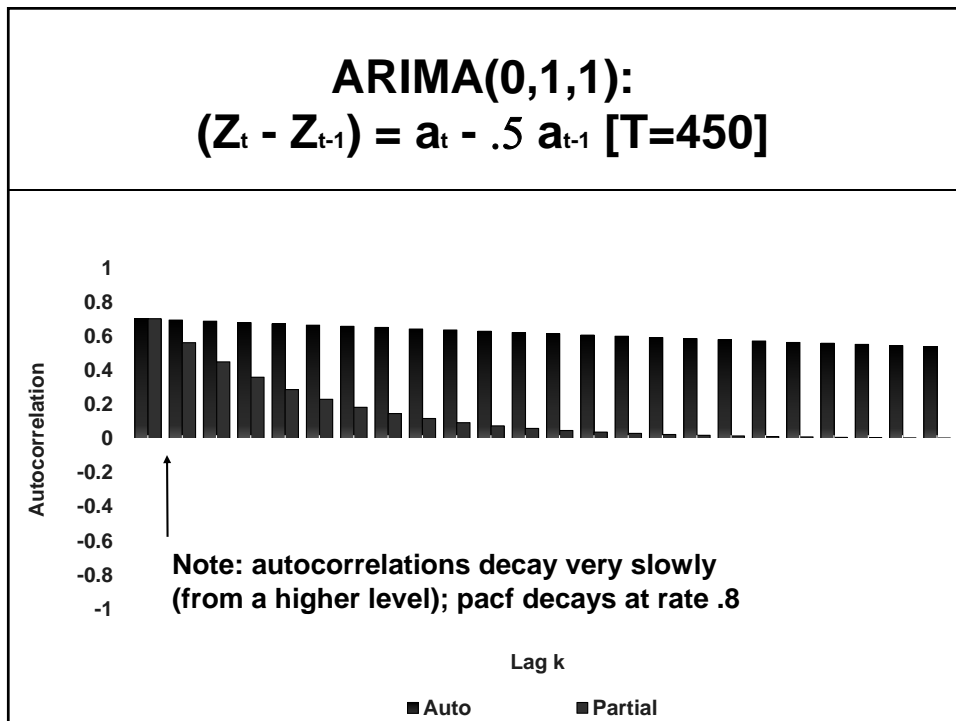
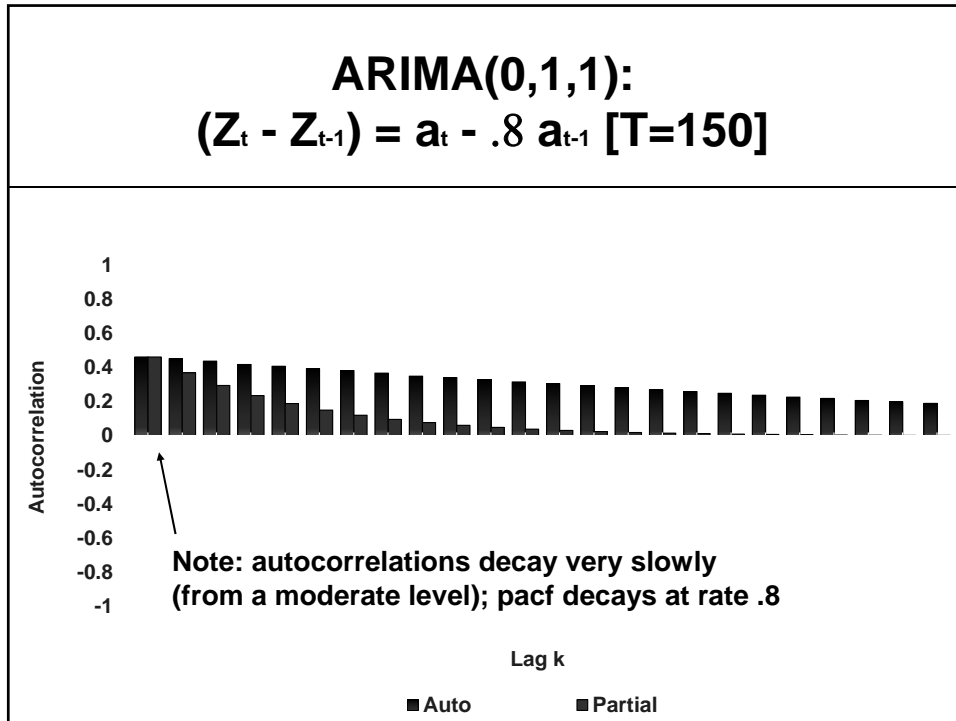
- 1) Autocorrelations decay or oscillate
 - because an AR model is equivalent to an infinite order MA process
- 2) Partial Autocorrelations decay or oscillate
 - because an MA model is equivalent to an infinite order AR process

Autoregressive Integrated Moving Average ARIMA(p,d,q) Models

- 1) ARMA model in the d^{th} differences of the data
- 2) First step is to find the level of differencing necessary
- 3) Next steps are to find the appropriate ARMA model for the differenced data
- 4) Need to avoid “overdifferencing”

ARIMA(0,1,1):
 $(Z_t - Z_{t-1}) = a_t - .8 a_{t-1} [T= 50]$



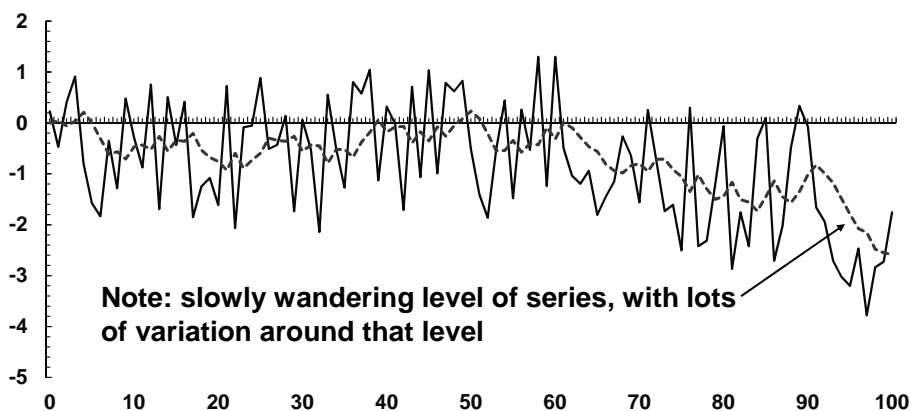


“Autocorrelations” for Nonstationary ARIMA Models

The sample autocorrelations decay very slowly and the level of the autocorrelations is dependent on the length of the sample (in this example $T = 50, 150,$ or 450)

- This would not be true if the series was stationary

$$\text{ARIMA}(0,1,1)$$
$$(Z_t - Z_{t-1}) = a_t - .8 a_{t-1}$$



Seasonal ARIMA(P,D,Q)_s Models

Just like ARIMA(p,d,q) models, except the gap between observations that affect one another is s periods, not 1 period

Example: ARIMA(1,0,0)₁₂ model [monthly AR(1)]

$$Z_t = \alpha + \phi_1 Z_{t-12} + e_t$$

- so the autocorrelations decay exponentially at lags 12, 24, 36, etc.
- partial autocorrelation at lag 12 = ϕ_1
 - after lag 12, they equal 0

Seasonal ARIMA(0,1,1)_s Models

This model occurs a lot in real data

- note that seasonal differencing removes a linear trend
- it also removes different fixed means
 - i.e., dummy variables
- if the MA parameter is close to 1, this "exponential smoothing" model implies a slowly wandering level for the series that is different for each period of the year

Seasonal Exponential Smoothing Forecasts

ARIMA(0,1,1)₁₂ model:

$$[Z_t - Z_{t-12}] = e_t - \theta_1 e_{t-12}$$

$$\hat{Z}_{t-12}(12) = Z_{t-12} - \theta_1 e_{t-12} = Z_{t-12} - \theta_1 [Z_{t-12} - \hat{Z}_{t-24}(12)]$$

$$= (1 - \theta_1) Z_{t-12} + \theta_1 \hat{Z}_{t-24}(12)$$

- so the forecast for next January is a weighted average of the most recent observation and the forecast for that observation (for Januarys)

Integrated Moving Average Models: Summary

- 1) Autocorrelations decay slowly
 - initial level is determined by how close MA parameter is to one
- 2) Partial Autocorrelations decay or oscillate
 - determined by MA parameter

Links

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